Efficiency of Earthquake Early Warning Systems

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Components of Early Warning System

- User Information (Alarm)
- Seismological Network plus communication
- Methodology (Parameter)

Question: Given a certain user requirement what is the best network configuration? what are the best parameters?

Introduction

- The simplest approach to earthquake early warning (EEW) is based on thresholds: when the ground motion at a given number of stations of the network exceeds a given threshold, an alarm is declared
- Or, rephrased: What are
 - a) the optimal station locations,
 - b) the optimal thresholds,
 - c) the minimum necessary number of stations and, in our case, the benefit of a given number of ocean bottom stations?
- As an example to address these questions, we use the case of Istanbul & the Sea of Marmara

Synthetic dataset



- Istanbul: seismic hazard determined by fault segments of North Anatolian fault below the Sea of Marmara
- > 5 segments (Böse et al., 2008)
- Istanbul is the user site for EEW
- ➤ 180 earthquakes with 4.5 ≤ M ≤ 7.5 simulated with FINSIM (Beresnev & Atkinson,1997) (extended to Pwaves, Böse et al., 2008) on a grid of stations (150 events on 5 segments, 30 smaller events randomly distributed)

Current early warning system



- Current EEW system implemented within the Istanbul Earthquake Rapid Response and Early Warning System (IERREWS, Erdik et al., 2003)
- 10 real-time stations along the shoreline of the Sea of Marmara (further 10 shall be added soon)
- 3 warn classes defined by thresholds 0.02g, 0.05g & 0.10g, which have to be exceeded at 3 stations within 5 sec

Principle of thresholds-based system



Optimization approach

- Start with an random station configuration of a given number (e.g. 10) on grid and 3 thresholds in the range 0.01g – 0.32g
- > Warning times for correctly classified events are determined
- Warning times are evaluated with a cost function based on a sigmoid centered around a certain t_{center} (e.g. 5 sec)



Optimization approach

- Two subgrids where stations can be placed in the GA: stations (a) on land and (b) in the Sea of Marmara
- This way, the benefit of adding a certain number of ocean bottom seismometers (OBS) (and their best positions!) can be easily evaluated

Chossifiend tione of events:

- Chresholds GAUseldtion current EEW system adaiting d
- without a direct link to ground motion to be expected

- the user site (Istanbul)! ass II: PGA in Istanbul $\ge 0.05g$ establish this link! Following PGA in Istanbul, we
- Classify the events and whinimize classification errors

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Problem: how to set reasonable t_{center}?



- Sigmoid function: a center time has to be chosen
- Question: what is the range of warning times that are reasonable to be expected?
- Possible answer from the distribution of maximum possible warning times (for fixed threshold, choosing for each event the station location on the grid where the threshold is first exceeded)

Max. t_{warn} di **Chosen t_{center} in our runs:**



Evaluation of current system



Optimization: warning on 1st exceedance



Full optimization: 10 land stations



Full optimization: 7 land stations, 3 OBS



Conclusions

- The presented methodology can optimize the seismic network (sites) and the parameter for early warning.
- Optimization approach as such not limited to thresholdbased systems, but might also be applicable when using e.g. predominant period as indicator for earthquake magnitude
- The current Istanbul EEW system performs quite well. There is however room for improvement, as the optimization shows:
 - by increasing class III threshold to avoid class III false alarms
 - by slightly modifying the station distribution
- Using three OBS would generally increase the available warning times by 2 – 3 sec on average (especially noticeable for class III events)